

Proof Search in Nested Sequent Calculi

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Sequent systems and modal logics

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E.g.:

$$\frac{\Gamma \vdash A}{\Box \Gamma \vdash \Box A} \text{ k}$$

$$\frac{\Box \Gamma \vdash A}{\Box \Gamma \vdash \Box A} \text{ 4}$$

Solutions: structures with sequents in them

The solution according to **internal approaches**:

Extend the sequent structure!

By now, there are many ways to do so:

- ▶ Higher-level sequents : Sequents of sequents of sequents of...
[Došen:'85]
- ▶ 2-sequents: Streams of sequents
[Masini:'92]
- ▶ Display calculi: structural connectives for all operators
[Belnap:'82, Wansing:'94, Kracht:'96]
- ▶ Nested sequents: Trees of sequents
[Kashima:'94, Brünnler:'06, Poggiolesi:'09]
- ▶ ...

The Question

What is the **simplest extension of the sequent structure** satisfying these desiderata for modal logics?

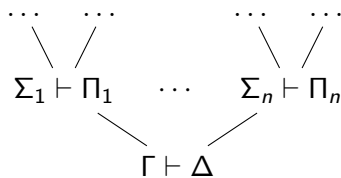
Case study: Nested sequents

Definition

([Brünnler:'09,Poggiolesi:'09])

A **nested sequent** is a finite tree whose nodes are labelled with sequents. The **interpretation** ι of this nested sequent is

$$\bigwedge \Gamma \rightarrow \bigvee \Delta \vee \bigvee_{i=1}^n \Box \iota(\Sigma_i \vdash \Pi_i).$$



Fact

The nested sequent calculus with modal rules \Box_R and \Box_L is sound and cut-free complete for modal logic K.

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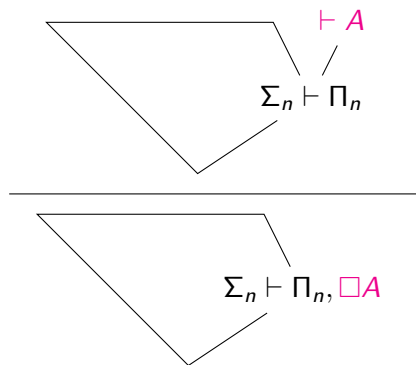
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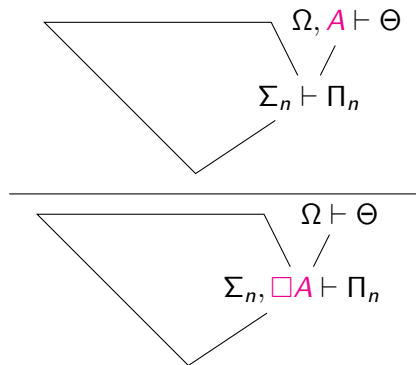
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Trees are nice, but can we go **simpler**?

Linear nested sequents

Definition

A **linear nested sequent** is a finite list of sequents, written

$$\Gamma_1 \vdash \Delta_1 // \dots // \Gamma_n \vdash \Delta_n$$

and interpreted as $\bigwedge \Gamma_1 \vdash \bigvee \Delta_1 \vee \square(\dots \square(\bigwedge \Gamma_n \vdash \bigvee \Delta_n) \dots)$.

The nested sequent system for \mathbb{K} yields the modal rules of **LNS $_{\mathbb{K}}$** :

$$\frac{\mathcal{G} // \Gamma \vdash \Delta // \Sigma, A \vdash \Pi // \mathcal{H}}{\mathcal{G} // \Gamma, \square A \vdash \Delta // \Sigma \vdash \Pi // \mathcal{H}} \square_L \quad \frac{\mathcal{G} // \Gamma \vdash \Delta // \vdash A}{\mathcal{G} // \Gamma \vdash \Delta, \square A} \square_R$$

Extensions, e.g. (lifted shamelessly from nested sequent calculi):

$$\frac{\mathcal{G} // \Gamma \vdash \Delta // A \vdash}{\mathcal{G} // \Gamma, \square A \vdash \Delta} d \quad \frac{\mathcal{G} // \Gamma \vdash \Delta // \Sigma, \square A \vdash \Pi // \mathcal{H}}{\mathcal{G} // \Gamma, \square A \vdash \Delta // \Sigma \vdash \Pi // \mathcal{H}} 4$$

Completeness for linear nested sequents

We could show completeness via cut elimination ... but it's easier!

Observation: The data structure of LNS is the same as that of a history in backwards proof search for a sequent calculus.

So we simply **simulate a sequent derivation in the last components:**
(\mathcal{G} is the history)

$$\frac{\frac{\Gamma \vdash A}{\Box \Gamma \vdash \Box A} \text{ k} \quad \vdots \mathcal{G}}{\Box \Gamma \vdash \Box A} \quad \rightsquigarrow \quad \frac{\frac{\mathcal{G} // \Box \Gamma \vdash \Box A // \Gamma \vdash A}{\mathcal{G} // \Box \Gamma \vdash \Box A} \Box_L}{\mathcal{G} // \Box \Gamma \vdash \Box A} \Box_R$$

Theorem

The LNS calculi for \mathbb{K} and extensions with axioms from d, t, 4 or d, 4, (4 \wedge 5) are cut-free complete and modular.

Corollary: Cut-free completeness of the nested sequent calculi.

Application: intuitionistic logic

The same idea connects Maehara's multi-succedent calculus and Fitting's nested sequent calculus for intuitionistic logic, e.g.:

Maehara:

$$\frac{\Gamma, A \vdash B}{\Gamma \vdash \Delta, A \supset B} \supset_R$$

Fitting (restricted to LNS):

$$\frac{\mathcal{G} // \Gamma \vdash \Delta // \Sigma, A \vdash \Pi // \mathcal{H}}{\mathcal{G} // \Gamma, A \vdash \Delta // \Sigma \vdash \Pi // \mathcal{H}} \text{Lift}$$

$$\frac{\mathcal{G} // \Gamma \vdash \Delta // A \vdash B}{\mathcal{G} // \Gamma \vdash \Delta, A \supset B} \supset_R$$

Maehara's rule is simulated by Fitting's \supset_R and Lift.

The quantifier rules are similar.

Theorem

The LNS calculus for (full) first-order intuitionistic logic (and hence also Fitting's nested sequent calculus) is cut-free complete.

Simply dependent bimodal logics

The language of *simply dependent bimodal logic* $KT \oplus_{\subseteq} S4$ contains two modalities \Box and \heartsuit , and the axioms are the KT axioms for \Box together with the $S4$ axioms for \heartsuit and the *interaction* axiom $\heartsuit A \supset \Box A$.

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$$\begin{array}{llll} \heartsuit A \supset \Box A & k_{\Box} \Box(A \supset B) \supset (\Box A \supset \Box B) & t_{\Box} \Box A \supset A & \frac{\vdash A}{\vdash \Box A} \text{ nec}_{\Box} \\ k_{\heartsuit} \heartsuit(A \supset B) \supset (\heartsuit A \supset \heartsuit B) & t_{\heartsuit} \heartsuit A \supset A & 4_{\heartsuit} \heartsuit A \supset \heartsuit \heartsuit A & \frac{\vdash A}{\vdash \heartsuit A} \text{ nec}_{\heartsuit} \end{array}$$

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$$\heartsuit A \supset \Box A \quad k_{\Box} \Box(A \supset B) \supset (\Box A \supset \Box B) \quad t_{\Box} \Box A \supset A \quad \frac{\vdash A}{\vdash \Box A} \text{ nec}_{\Box}$$

$$k_{\heartsuit} \heartsuit(A \supset B) \supset (\heartsuit A \supset \heartsuit B) \quad t_{\heartsuit} \heartsuit A \supset A \quad 4_{\heartsuit} \heartsuit A \supset \heartsuit \heartsuit A \quad \frac{\vdash A}{\vdash \heartsuit A} \text{ nec}_{\heartsuit}$$

$$\frac{\mathcal{G} // * \Gamma \vdash \Delta // \Box \vdash A}{\mathcal{G} // * \Gamma \vdash \Delta, \Box A} \Box_{R\Box} \quad \frac{\mathcal{S}\{\Gamma \vdash \Delta // \Box \Sigma, A \vdash \Pi\}}{\mathcal{S}\{\Gamma, \Box A \vdash \Delta // \Box \Sigma \vdash \Pi\}} \Box_{L}$$

$$\frac{\mathcal{S}\{\Gamma \vdash \Delta // \Box \Sigma, \heartsuit A \vdash \Pi\}}{\mathcal{S}\{\Gamma, \heartsuit A \vdash \Delta // \Box \Sigma \vdash \Pi\}} \heartsuit_{L\Box} \quad \frac{\mathcal{G} // * \Gamma \vdash \Delta // \heartsuit \vdash A}{\mathcal{G} // * \Gamma \vdash \Delta, \heartsuit A} \heartsuit_{R\heartsuit}$$

$$\frac{\mathcal{S}\{\Gamma \vdash \Delta // \heartsuit \Sigma, \heartsuit A \vdash \Pi\}}{\mathcal{S}\{\Gamma, \heartsuit A \vdash \Delta // \heartsuit \Sigma \vdash \Pi\}} \heartsuit_{L\heartsuit} \quad \frac{\mathcal{S}\{\Gamma, \Box A, A \vdash \Delta\}}{\mathcal{S}\{\Gamma, \Box A \vdash \Delta\}} t_{\Box} \quad \frac{\mathcal{S}\{\Gamma, \heartsuit A, A \vdash \Delta\}}{\mathcal{S}\{\Gamma, \heartsuit A \vdash \Delta\}} t_{\heartsuit}$$

Non-normal modal logics

Classical modal logic E: congruence rule

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Extensions:

$$\text{M} \quad \Box(A \wedge B) \supset (\Box A \wedge \Box B) \quad \text{C} \quad (\Box A \wedge \Box B) \supset \Box(A \wedge B) \quad \text{N} \quad \Box \top$$

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$$\frac{\mathcal{G} // \Gamma \vdash \Delta //^m \vdash B}{\mathcal{G} // \Gamma \vdash \Box B, \Delta} \Box_R^m$$

$$\frac{\mathcal{G} // \Gamma \vdash \Delta // \Sigma, A \vdash \Pi}{\mathcal{G} // \Gamma, \Box A \vdash \Delta //^m \Sigma \vdash \Pi} \Box_L^m$$

$$\frac{\mathcal{G} // \Gamma \vdash \Delta //^m \Sigma, A \vdash \Pi}{\mathcal{G} // \Gamma, \Box A \vdash \Delta //^m \Sigma \vdash \Pi} \Box_L^c$$

$$\frac{\mathcal{G} // \Gamma \vdash \Delta // \vdash B}{\mathcal{G} // \Gamma \vdash \Box B, \Delta} \Box_R^n$$

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$$\frac{\mathcal{G} // \Gamma \vdash \Delta // {}^m \vdash B}{\mathcal{G} // \Gamma \vdash \Box B, \Delta} \Box_R^m$$

$$\frac{\mathcal{G} // \Gamma \vdash \Delta // \Sigma, A \vdash \Pi}{\mathcal{G} // \Gamma, \Box A \vdash \Delta // {}^m \Sigma \vdash \Pi} \Box_L^m$$

$$\frac{\mathcal{G} // \Gamma \vdash \Delta // {}^m \Sigma, A \vdash \Pi}{\mathcal{G} // \Gamma, \Box A \vdash \Delta // {}^m \Sigma \vdash \Pi} \Box_L^c$$

$$\frac{\mathcal{G} // \Gamma \vdash \Delta // \vdash B}{\mathcal{G} // \Gamma \vdash \Box B, \Delta} \Box_R^n$$

$$\text{LNS}_M \{ \Box_R^m, \Box_L^m \} \quad \text{LNS}_{MC} \{ \Box_R^m, \Box_L^m, \Box_L^c \}$$

$$\text{LNS}_{MN} \{ \Box_R^m, \Box_L^m, \Box_R^n \} \quad \text{LNS}_{MCN} \{ \Box_R^m, \Box_L^m, \Box_L^c, \Box_R^n \}$$

Non-monotone non-normal modal logics

For extensions of classical modal logic E not containing the monotonicity axiom M we need to store more information about the unfinished premisses.

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$$\frac{\mathcal{G} // \Gamma \vdash \Delta //^e(\vdash B; B \vdash)}{\mathcal{G} // \Gamma \vdash \Box B, \Delta} \Box_R^e$$

$$\frac{\mathcal{G} // \Gamma \vdash \Delta // \Sigma, A \vdash \Pi \quad \mathcal{G} // \Gamma \vdash \Delta // \Omega \vdash A, \Theta}{\mathcal{G} // \Gamma, \Box A \vdash \Delta //^e(\Sigma \vdash \Pi; \Omega \vdash \Theta)} \Box_L^e$$

$$\frac{\mathcal{G} // \Gamma \vdash \Delta //^e(\Sigma, A \vdash \Pi; \Omega \vdash \Theta) \quad \mathcal{G} // \Gamma \vdash \Delta // \Omega \vdash A, \Theta}{\mathcal{G} // \Gamma, \Box A \vdash \Delta //^e(\Sigma \vdash \Pi; \Omega \vdash \Theta)} \Box_L^{ec}$$

$$\text{LNS}_E \quad \{ \Box_R^e, \Box_L^e \}$$

$$\text{LNS}_{EC} \quad \{ \Box_R^e, \Box_L^e, \Box_L^{ec} \}$$

Labelled line sequent systems

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$$\vdots$$
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$$x_{n-1} R x_n, x_0 : \Gamma_0, \dots, x_n : \Gamma_n \vdash x_0 : \Delta_0, \dots, x_n : \Delta_n$$
$$\frac{x R y, X \vdash Y, y : A}{z R x, X, \vdash Y, x : \Box A} \Box_R$$

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A LNS calculus is **end-active** if in all its rules the rightmost components of the premisses are active and the only active components (in premisses and conclusion) are the two rightmost ones.

Focused labelled line sequent systems

$$\frac{zRx : \Gamma; X, x : A, x : B \Rightarrow Y; \Delta}{zRx : \Gamma; X, x : A \wedge B \Rightarrow Y; \Delta} \wedge_L \quad \frac{zRx : \Gamma; X, x : A \Rightarrow Y, x : B; \Delta}{zRx : \Gamma; X \Rightarrow Y, x : A \supset B; \Delta} \supset_R$$

$$\frac{zRx : \Gamma, x : B_b; X \Rightarrow Y; \Delta}{zRx : \Gamma; X, x : B_b \Rightarrow Y; \Delta} \text{store}_L \quad \frac{zRx : \Gamma; X \Rightarrow Y; \Delta, x : A_b}{zRx : \Gamma; X \Rightarrow Y, x : A_b; \Delta} \text{store}_R$$

$$\frac{}{zR[x] : \Gamma; X, x : A \rightarrow \cdot; \Delta, x : A} \text{init}$$

$$\frac{zR[x] : \Gamma; X \rightarrow \cdot; \Delta}{zRx : \Gamma; X \Rightarrow \cdot; \Delta} D \quad \frac{xRy : \cdot; X \Rightarrow Y; \Delta}{[x]Ry : \cdot; X \rightarrow Y; \Delta} R$$

$$\frac{[x]Ry : \Gamma; X \rightarrow y : A; \Delta}{zR[x] : \Gamma; X \rightarrow \cdot; \Delta, x : \Box A} \Box_R \quad \frac{[x]Ry : \Gamma; X, y : A \rightarrow Y; \Delta}{[x]Ry : \Gamma, x : \Box A; X \rightarrow Y; \Delta} \Box_L$$

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Focusing effectively blocks derivations where propositional rules are applied between modal ones. Hence we reconcile the added superior expressiveness and modularity of nested sequents with the computational behavior of the standard sequent framework.

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- ▶ This enables us to both: (i) use the rich linear logic meta-level theory in order to reason about the specified systems; and (ii) use a linear logic prover in order to do automatic proof search in those systems (<http://subsell.logic.at/nestLL/>).

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$$\text{(init)} \quad \exists A, x. [x : A]^\perp \otimes [x : A]^\perp \otimes \text{atomic}(A)$$

$$\text{(\wedge}_l\text{)} \quad \exists A, B, x. [x : A \wedge B]^\perp \otimes [x : A] \wp [x : B]$$

$$\text{(\wedge}_r\text{)} \quad \exists A, B, x. [x : A \wedge B]^\perp \otimes [x : A] \& [x : B]$$

$$\text{(\Box}_R\text{)} \quad \exists A, B, x. [x : \Box A]^\perp \otimes \forall y. ([y : A] \wp R(x, y)) \otimes \exists z. R(z, x)^\perp$$

$$\text{(\Box}_L\text{)} \quad \exists A, B, x. [x : \Box A]^\perp \otimes \exists y. ([y : A] \wp R(x, y)) \otimes R(x, y)^\perp$$

Conclusion and future work

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This is a significant step towards a better understanding of proof theory for modal logics in general, and it opens an avenue for research in proof search for a broad set of systems (not only modal).

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- ▶ our methods work for logics which are not based on a cut-free sequent calculus, such as the calculi for K5 or KB?

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Summing up we:

- ▶ proposed focused nested sequent systems for a number of modal logics (including a non-trivial bimodal logic and non-normal logics) which match the complexity of existing sequent calculi;
- ▶ specified the labelled systems in linear logic, thereby obtaining automatic provers for all of them.

This is a significant step towards a better understanding of proof theory for modal logics in general, and it opens an avenue for research in proof search for a broad set of systems (not only modal).

Future work:

- ▶ applicability of this approach to logics based on non-classical propositional logic such as constructive modal logics;
- ▶ our methods work for logics which are not based on a cut-free sequent calculus, such as the calculi for K5 or KB?
- ▶ automatically extract focused systems from LLF specifications.