A heuristic for minimizing weighted carry-over effects in round robin tournaments

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Abstract The carry-over effects value is one of the various measures one can consider to assess the quality of a round robin tournament schedule. We introduce and discuss a new, weighted variant of the minimum carry-over effects value problem. The problem is formulated by integer programming and an algorithm based on the hybridization of the Iterated Local Search metaheuristic with a multistart strategy is proposed. Numerical results are presented.

Keywords: Carry-over; round robin; tournaments; sports scheduling; timetabling; heuristics; iterated local search

1 Motivation

Sports optimization has been attracting the attention of an increasing number of researchers and practitioners in multidisciplinary areas such as operations research, scheduling theory, constraint programming, graph theory, combinatorial optimization, and applied mathematics. Kendall et al. [1] surveyed state-of-the-art applications and methods for solving optimization problems in sports scheduling. Rasmussen and Trick [2] reviewed scheduling problems in round robin tournaments, which are of special importance due to their practical relevance and interesting mathematical structure.

There are many relevant aspects to be considered in the determination of the best fixture for a tournament. In some situations, one seeks for a schedule minimizing the total traveled distance, as in the case of the traveling tournament problem [3] and in that of its mirrored variant [4], which is common to many tournaments in South

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America. Other problems attempt to minimize the number of breaks, i.e., the number of pairs of consecutive home games or consecutive away games. Ribeiro and Urrutia [5] tackled the scheduling of the Brazilian national football tournament, in which the objective function consists of maximizing the number of games that may be broadcast by open TV channels, so as to increase the revenues from broadcast rights.

The minimization of the *carry-over effects value* [6] is a fairness criterion leading to an even distribution of the sequence of games along the schedule.

A major issue in the strategy of a team (or an athlete), in particular in long competitions, consists of balancing their efforts over the competition. If a team plays against a weak opponent, it is likely to be in better shape to play in the next round than if it had played against a hard opponent before. Teams that play against strong opponents will very likely be more tired for their next game. Therefore, it is likely that a team (or an athlete) makes much less effort playing against an opponent that played before against a very strong contestant, than it would make against an opponent that faced an easy contestant.

The above situation is particularly true in the case of sports which require a great amount of physical effort (such as wrestling, rugby, and martial arts). In this sort of sports, it is not uncommon that a team (or an athlete) plays several games in a row, making a sequence of very tired (resp. well reposed) opponents very attractive (resp. unattractive). Some fixtures may contain several of such sequences of easier or harder games assigned to one or more teams. This situation does not characterize a fair schedule and is highly undesirable in any tournament. To illustrate this effect, suppose a Karate-Do or Judo competition. There is no weight division in open-weight categories of such sports: a physically weak athlete may fight a strong one. A contestant that has just fought a very strong opponent will possibly be very tired (and even wounded) in his/her next fight. This would deteriorate his/her performance, giving to the next opponent a strong advantage that otherwise he/she would not have.

Suppose that team A plays team C right after playing team B. If team B is much stronger than the other competitors, then team C will possibly take some advantage over team A in their game. This is due to the great effort team A has made in its previous game. This type of situation in which one of the teams may be benefited should be avoided or, at least, minimized.

We say that a team C receives a carry-over effect due to team B if there is a team A that plays C just after its game against B. We consider a single round robin tournament played by n (even) teams, in which every team plays each other exactly once. Figure 1 (a) displays a matrix describing a hypothetical tournament fixture, whose entry in row i and column j informs the team playing against team j in round i. One may count the number of carry-over effects each team gives to every other in the fixture of a round robin tournament and then build the *carry-over effects matrix*. Each entry in row i and column j of this matrix indicates the number of carry-over effects team i gives to team j. Figure 1 (b) presents the underlying carry-over effects matrix associated with the fixture represented in Figure 1 (a).

A fair tournament regarding carry-over effects is one in which the latter are evenly distributed over the cells of the carry-over effects matrix and the total carry-over effects value is minimized. The problem of minimizing the carry-over effects value was originally proposed by Russell [6]. In this work, we extend the latter by the minimization of the *weighted carry-over effects value*. This new, weighted problem is introduced and formulated in the next section. Section 3 reviews previous solution approaches for the unweighted original problem and describes a heuristic based on the hybridization of

	A	в	\mathbf{C}	D	Е	F	G	н		А	В	\mathbf{C}	D	\mathbf{E}	\mathbf{F}	\mathbf{G}	Η
	H	C	B	E	D	G	F		Α	0	0	3	0	1	2	1	0
2	C	D	A	B	G	Н	Ē	F	В	5	0	0	0	1	0	0	1
3	D	Ē	F	A	В	C	H	G	C	0	1	0	3	0	3	0	0
4	E	F	H	G	Ā	B	D	č	D	0	2	0	0	2	0	3	0
5	F	\mathbf{G}	\mathbf{E}	Н	\mathbf{C}	Α	В	D	E	1	1	0	2	0	2	0	1
6	G	Η	D	\mathbf{C}	\mathbf{F}	\mathbf{E}	Α	В	F G	0	0	0	$\begin{array}{c} 0\\ 0\end{array}$	$\frac{2}{0}$	0 0	$\frac{3}{0}$	$\frac{2}{3}$
7	В	Α	G	\mathbf{F}	Η	D	\mathbf{C}	\mathbf{E}	Н	1	$\frac{3}{0}$	1 3	$\frac{0}{2}$	1	0	0	0 0
				(a)					11	1	0	5	(b)	1	0	0	0

Fig. 1 (a) Fixture of a tournament with eight teams and (b) its carry-over effects matrix.

the Iterated Local Search metaheuristic with a multistart strategy for approximately solving the weighted variant. Numerical results are reported and discussed in Section 4. Concluding remarks are drawn in the last section.

2 Weighted formulation

A single round robin tournament is one in which each team plays every other exactly once. The games take place along a predefined period of time organized into rounds or slots. A compact tournament has a minimum number of rounds. A compact single round robin tournament with n (even) teams has n - 1 rounds.

For a given compact single round robin schedule with n teams, one says that team i gives a carry-over effect to team j if some other team plays consecutively against teams i and j, i.e., some team plays against team i in round t and against team j in round t+1 for some $t \in \{1, \ldots, n-1\}$, where the rounds are considered cyclically (i.e., round n-1 is followed by the first round). If team i is a very strong or very weak team and several teams play consecutively against teams i and j in this order, then team j may be, respectively, handicapped or favored compared with other teams. In an "ideal" schedule with respect to carry-over effects, no teams i, j, x, y should exist such that teams x and y both play against team j immediately after playing against team i.

The carry-over effects matrix $C = (c_{ij})$, with i, j = 1, ..., n, has been introduced to measure the balance of a tournament with respect to this criterion. Each entry c_{ij} of this matrix counts the number of carry-over effects given by team i to team j. It can be seen that $c_{ii} = 0$ and $\sum_{j=1}^{n} c_{ij} = \sum_{i=1}^{n} c_{ij} = n-1$ for all rows and columns i, j = 1, ..., n. The quality of a schedule with respect to carry-over effects is measured by the carry-over effects value $\sum_{i=1}^{n} \sum_{j=1}^{n} c_{ij}^2$. An ideal or balanced schedule is one in which the lower bound value n(n-1) is achieved, i.e., all non-diagonal elements of the corresponding matrix C are equal to one.

The original (unweighted) carry-over effects value minimization problem does not consider any information with respect to the relative strengths of the teams: all carryover effects have the same unit weight. However, in real sports competitions it is very likely that the organizers do have an initial estimate of how well a specific team should perform in the competition, considering e.g. its ranking in last year's competition, its traditions, the quality of its players, and the support of its fans in its home games. Noronha et al. [7] provide a concrete example of a competition (the Chilean football tournament) in which the teams are classified a priori according to some of these criteria in the effort to build a fair schedule. Therefore, one may conclude that the minimization of the carry-over effects value does not guarantee a fair schedule. In fact, a broader approach consists of assigning a weight w_{ij} to every ordered pair (i, j) of teams, based on their relative strengths or handicaps, and minimizing the total weighted carry-over effects value.

For every pair of teams i, j = 1, ..., n (with $i \neq j$) and for every round k = 1, ..., n (with rounds cyclically represented, such as that the round n - 1 is followed by the first round), we define the binary variable $y_{kij} = 1$ if and only if team *i* plays against team *j* in round *k*, with $y_{kij} = 0$ otherwise. We also define the number of carry-over effects given by team *i* to team *j* as

$$z_{ij} = \sum_{\ell=1}^{n} \sum_{k=1}^{n-1} y_{k\ell i} \cdot y_{(k+1)\ell j},$$
(1)

for $i \neq j$; $z_{ij} = 0$ if i = j. The integer programming formulation of the weighted carry-over effects value minimization problem is presented below:

$$\min \sum_{i=1}^{n} \sum_{j=1}^{n} w_{ij} \cdot z_{ij}^2$$
(2)

$$y_{kij} = y_{kji}, \qquad i, j, k = 1, \dots, n \tag{3}$$

$$\sum_{i=1}^{n} y_{kij} = 1, \qquad j, k = 1, \dots, n$$
(4)

$$\sum_{k=1}^{n-1} y_{kij} = 1, \qquad i, j = 1, \dots, n : i \neq j$$
(5)

$$y_{kii} = 0, \qquad i, k = 1, \dots, n$$
 (6)

$$y_{nij} = y_{1ij}, \qquad i, j = 1, \dots, n$$
 (7)

$$y_{kij} \in \{0, 1\}, \qquad i, j, k = 1, \dots, n.$$
 (8)

The objective function (2) minimizes the weighted sum of carry-over effects. Constraints (3) ensure that variables $y_{kij} = y_{kji}$ are the same or, alternatively, that the game between teams *i* and *j* is the same as that between teams *j* and *i* (there is a unique game between teams *i* and *j* in a single round robin tournament). Constraints (4) enforce that every team plays exactly once in each round of a compact schedule. Constraints (5) and (6) guarantee that each team plays exactly once against every other team. Constraints (7) enforce that the *n*-th round is equivalent to the first. Constraints (8) impose the binary requirements on the variables.

3 Hybrid heuristic for weighted minimization

Russell [6] proposed a construction algorithm for the unweighted problem that generates fixtures matching the lower bound to the carry-over effects value when n is a power of two. The method proposed by Anderson [8] obtained solutions that are still the best known to date for unweighted instances. It makes use of algebraic structures called *starters* [9] to generate schedules. However, the approach presumes that a suitable starter is known beforehand, which may imply in large computation times.

Trick [10] developed a constraint programming method that made it possible to prove the optimality of Russell's method for n = 6. Henz, Müller, and Thiel [11] improved the solution obtained by the previous approach for n = 12, also using constraint programming. Miyashiro and Matsui [12] developed a time-consuming heuristic based on random permutations of the rounds of fixtures created by the polygon method [13]. They reported more than two days of computation time for $n \ge 18$.

The above algorithms do not explore different strategies to generate the initial fixtures, which limits the quality of the solutions they find. Furthermore, some of them are computationally expensive and not appropriate for the weighted variant.

We propose a tailored heuristic for the minimization of weighted carry-over effects. This heuristic is based on the hybridization of the Iterated Local Search (ILS) metaheuristic [14,15] with a multistart strategy. It has two main steps: a multistart phase and an ILS phase. A complete run comprises a number of independent sequences of these two steps and returns the best solution found. The multistart phase generates 100 initial solutions, each of them obtained by a constructive method followed by a local search procedure. The best solution found during the multistart phase is used as the starting point for the ILS phase. The main steps of the pseudo-code of the hybrid heuristic corresponding to Algorithm 1 are described in detail in the next sections.

3.1 Construction method to build initial solutions

A factor of a graph G = (V, E) is a subgraph G' = (V, E') of G, with $E' \subseteq E$. A factor G' is a 1-factor if all its nodes have their degrees equal to one. A factorization F of G is a set of edge-disjoint factors of G, such that the union of their edge-sets is equal to E. A factorization of G formed exclusively by 1-factors is said to be a 1-factorization. In an ordered 1-factorization of G, its 1-factors are taken in a fixed order.

There is a one-to-one correspondence between 1-factorizations and round robin schedules. If each team is assigned to a vertex of G, each edge of the latter corresponds to a game. The games in each round correspond to the edges of a 1-factor, making the entire ordered 1-factorization equivalent to the complete tournament fixture.

The rounds of a tournament schedule can be freely permuted without violating any of its properties. Therefore, new schedules can be generated by picking the rounds of a given schedule in any possible order.

The construction method first generates one starting fixture in line 2 of Algorithm 1, using any of the two approaches described below. The first approach is the well known *polygon method* [13], which gives the so-called canonical 1-factorization [16]. It can be used for any value of n. Assuming the teams are numbered as $1, \ldots, n$, the edge-set of the 1-factor corresponding to round k is given by $\{(k,n)\} \cup \{(a(k,\ell), b(k,\ell)) : \ell = 1, \ldots, n/2 - 1\}$, for $k = 1, \ldots, n - 1$, with

$$a(k,\ell) = \begin{cases} k+\ell, & \text{if } (k+\ell) < n, \\ k+\ell-n+1, & \text{if } (k+\ell) \ge n, \end{cases}$$
(9)

and

$$b(k,\ell) = \begin{cases} k-\ell, & \text{if } (k-\ell) > 0, \\ k-\ell+n-1, & \text{if } (k-\ell) \le 0. \end{cases}$$
(10)

The second approach [16, 17] can be applied whenever n is a multiple of four. It first separates the teams in two sets $V_1 = \{1, \ldots, n/2\}$ and $V_2 = \{n/2 + 1, \ldots, n\}$. The first n/2 rounds are made up only by games with one team in V_1 and the other in V_2 . The games scheduled for round k correspond to the edges of the factor whose edge-set is defined as $\{(\ell, c(k, \ell)) : \ell = 1, \ldots, n/2\}$, for $k = 1, \ldots, n/2$, with

$$c(k,\ell) = (k+\ell-2) \mod (n/2) + n/2 + 1.$$
(11)

Each of the last n/2-1 remaining rounds is formed by picking and putting together one 1-factor from a 1-factorization of the complete graph associated with V_1 and one 1-factor from a 1-factorization of the complete graph associated with V_2 .

The loop in lines 3 to 7 builds each of the 100 initial solutions in line 4 as follows. First, two rounds of the starting fixture are randomly selected and used as the two first rounds of the new solution. In each subsequent step, one still unused round of the starting fixture is selected to be used in the current, incomplete fixture. This process continues, until a complete solution is obtained. The rules used for selecting and placing rounds of the starting fixture in the incomplete solution under construction mimic those in the well known *nearest neighbor* and *arbitrary insertion* heuristics for the traveling salesman problem [18, 19]:

 nearest neighbor heuristic: select the unused round which causes the minimum increment in the weighted carry-over effects value and place it as the last in the solution under construction. arbitrary insertion heuristic: randomly select any unused round and insert it between the two rounds which minimize the increase in the weighted carry-over effects value.

One of these strategies is randomly chosen with equal probability to generate a new initial solution at each iteration of the multistart phase.

3.2 Local search

The initial solutions built by the construction method described in the previous section are tentatively improved by local search in line 5 of Algorithm 1. We use a local search procedure following the Variable Neighborhood Descent (VND) [20, 21] strategy. The best improving move in each neighborhood is applied to the current solution. The following neighborhood structures described by Costa et al. [22] (see also [4]) are used in this order:

- *Team swap* (TS): a move in this neighborhood corresponds to swapping all opponents of a given pair of teams over all rounds, which is the same as swapping two columns of the matrix representing the fixture.
- Round swap (RS): a move in this neighborhood consists of swapping all games of a given pair of rounds, which is the same as swapping two rows of the matrix representing the fixture.
- Partial team swap (PTS): for any round r and for any two teams t_1 and t_2 , let S be a minimum cardinality subset of rounds including round r in which the opponents of teams t_1 and t_2 are the same. A move in this neighborhood corresponds to swapping the opponents of teams t_1 and t_2 over all rounds in S.
- Partial round swap (PRS): for any team t and for any two rounds r_1 and r_2 , let U be a minimum cardinality subset of teams including team t in which the opponents of the teams in U in rounds r_1 and r_2 are the same. A move in this neighborhood consists of swapping the opponents of all teams in U in rounds r_1 and r_2 .

If the locally optimal solution (with respect to neighborhoods TS, RS, PTS, and PRS) obtained by the VND local search strategy improves the best initial solution, then the latter is updated in line 6.

3.3 Iterated local search

The best initial solution obtained at the end of the multistart phase is copied in line 8 of Algorithm 1 to be used as the starting solution S by the ILS phase in lines 9-14, until some stopping criterion is met.

Each ILS iteration starts in line 10 by a perturbation of the current solution S. The perturbation consists of a sequence of random moves within the *game rotation* (GR) neighborhood introduced by Ribeiro and Urrutia [4]. For each move, a randomly generated game is enforced to be changed from the round where it is currently played to a different, randomly selected round. This first change is followed by a sequence of modifications leading to a feasible solution S', according to the ejection chain mechanism proposed by Glover [23].

A bias is introduced in the perturbation procedure, to drive the move away from pure randomness. Although one cannot know beforehand the effect of a complete ejection chain move on the weighted carry-over effects value of a solution, the increment (or decrement) implied by the first step of the chain can be easily evaluated. The bias consists simply of enforcing the game with the smallest first increment.

The same local search procedure described in Section 3.2 is applied to the perturbed solution S' in line 11. The current solution S is replaced by S' in line 12 if the carry-over effects value of the latter is less than or equal to (1+b) times the carry-over effects value of the former. The value of parameter b doubles after every 2n iterations without the modification of the current solution. It is reset to its initial value whenever the current solution is updated, following the same strategy already used in [4]. Finally, the best known solution S^* is updated in line 13. The ILS phase stops if line 14 detects that a maximum number of deteriorating moves have been accepted since the last time the best solution was updated.

4 Computational results

Each instance is defined by the number of teams and by a weighted matrix of carry-over effects. Four classes of weighted instances have been generated for the computational experiments:

- random instances: weights are randomly generated in the interval [1, 2n]. Three matrices identified by letters A, B and C have been generated for each value of n.
- linear instances: a strength in the interval [1, n] is assigned to each team. For simplicity, the strength of team *i* is made equal to *i*. Each weight w_{ij} is defined as the absolute value of the difference between the strengths of teams *i* and *j*.
- perturbed linear instances: each weight of a linear instance is increased by an individual perturbation, randomly generated in the interval [-n/2, n/2]. Three different instances identified by letters A, B and C are generated for each value of n. Absolute values are taken whenever the perturbation leads to a negative weight.
- real-life inspired instances: these six instances are derived from the last six issues of the Brazilian football championship. The strength of each team is given by the number of points it obtained in the previous year. As for the linear instances, each weight w_{ij} is defined as the absolute value of the difference between the strengths of teams *i* and *j*.

Data of the weighted instances is available from the authors for benchmarking purposes at http://www.ic.uff.br/~celso/grupo/Weighted_carry-over_instances.zip. We also considered instances made up only of unit costs, which are equivalent to those of the original, unweighted problem.

The computational experiments were performed on an AMD Athlon 64 X2 machine with 2.3 GHz and one GB of RAM memory. The code was implemented in C++ and compiled with the GNU C/C++ compiler (GCC) version 4.2.4 under Ubuntu Linux 8.04.

4.1 Tuning

The strategy used to generate the starting fixtures sensibly changes the quality of the solutions found. We tested two different alternatives to obtain the starting fixture whenever n is a multiple of four. In the first, only the polygon method is used and canonical factorizations are produced. In the second, the two methods described in Section 3.1 are indistinctly employed to obtain 1-factorizations.

We observed from preliminary results that the main parameters influencing the behavior of the ILS phase are the maximum number of deteriorating moves accepted before termination of this phase, the number of ejection chain (game rotation) moves applied in each perturbation, and the initial value for b. We also observed that reasonable values for these parameters are:

 $\begin{array}{ll} \mbox{maximum number of deteriorating moves: } \{10, 100, 200\} \\ \mbox{number of ejection chain moves in a perturbation: } \{1, 5, 10\} \\ \mbox{initial value for } b: \{0.01, 0.05, 0.10\} \end{array}$ (12)

To assess the behavior of the algorithm with respect to parameter values and implementation strategies, we ran the algorithm on three unweighted instances for which n is a multiple of four – namely, for n = 12, 16, and 20. For each of these instances, we tested every possible combination of the above parameter values with the two alternatives for generating the initial fixture. For each configuration, we took average results over three independent runs.

We first discuss the best strategy to generate the initial fixture. Table 1 displays the results obtained by each of the two alternatives for each problem size: average solution value, best solution value, average computation time (in seconds), and longest computation time (in seconds) over the three runs for each combination of the parameter values. The upper part of this table gives the results for the first alternative, based exclusively on canonical factorizations. The lower part reports results for the second alternative, which makes use of both approaches. Although the first alternative (upper part) is less time consuming than the second, the latter (lower part) seems to find better (or comparable) solutions. In consequence, we selected the second alternative to generate the initial fixture.

Strategy	n	COEV (avg.)	COEV (best)	Time (avg.)	Time (max.)
Canonical	12	192.000	192.000	3.519	4.000
factorizations	16	306.914	304.444	178.765	183.296
	20	489.852	488.444	20.790	21.296
Both	12	167.630	164.370	64.790	69.111
factorizations	16	267.630	258.519	244.827	263.926
	20	492.000	490.370	54.481	62.481

Table 1 COEV values and computation times in seconds for two different strategies for thegeneration of initial fixtures.

To choose the most appropriate configuration of parameter values, we ran the hybrid heuristic (using the second alternative to generate the initial fixture) with all of the 27 possible combinations of parameter values. We collected minimum and maximum results obtained over three runs of each instance tested with n = 12, 16, and 20. For each of them, the results found with each combination were normalized to the interval [0, 1]. Finally, we computed average normalized results over all instances considered. The plot in Figure 2 presents the average normalized carry-over effects value and the average normalized running time for each combination. Similarly, the plot in Figure 3 displays

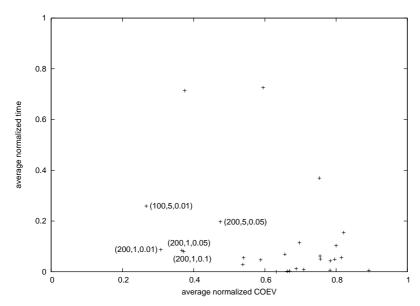


Fig. 2 Average normalized results obtained with different combinations of parameters.

the average normalized best carry-over effects value and the average normalized longest computation time for each combination.

Each point in these plots represents a unique combination of parameter values. The five winning combinations closest to the ideal point (0,0) are the same for both plots. They are identified and labeled with the corresponding maximum accepted number of deteriorating moves, number of ejection chain moves in a perturbation, and initial value of parameter b (in this order).

Since four out of the five best combinations accept a maximum of 200 deteriorating moves before termination of the ILS phase, this value was selected for the first parameter. The number of ejection chain moves in a perturbation is set to one, since three out of the five best points plotted correspond to this value. The best choice for the initial value of parameter b is less evident from these results. For sake of robustness, we selected b = 0.01.

4.2 Weighted instances

The hybrid heuristic was run five times for each instance, with the parameter values and implementation strategies as selected above. Average and best carry-over effects values and average and worst computation times in seconds over five runs are reported for each class of weighted test instances.

Results for the random instances are shown in the upper part of Table 2. These instances present the smallest computation times over all classes. The ILS phase was always able to improve the solutions found in the multistart phase, except for the three smallest instances.

We consider next the results for linear instances, reported in the lower part of Table 2. The ILS phase improved the solutions found in the multistart phase for all

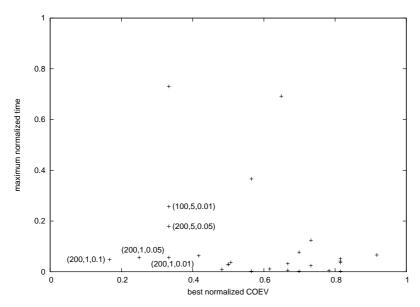


Fig. 3 Extremal normalized results obtained with different combinations of parameters.

instances with $n \ge 8$. The computation times are much greater than those observed for the previous class of instances. This seems to be particularly true for the instance with 20 teams.

Results for perturbed linear instances are shown in the upper part of Table 3. As for the two previous classes, the ILS phase always improved the best solution found in the multistart phase, except for the three smallest instances. The computational times are greater than those observed for the random and linear classes.

Finally, the results obtained for the set of real-life inspired instances are shown in the lower part of Table 3. This class presents the largest computation times for the instances with n = 20. This seems to be due to the fact that the weights in this class are more diverse than in any other.

4.3 Validation: unweighted instances

To validate the proposed hybrid heuristic, we also applied it to instances of the original unweighted problem. These instances are equivalent to weighted instances with unit weights. Figure 4 displays the best known solution values known to date and that obtained by the hybrid ILS heuristic for n = 4, ..., 16. The heuristic matched the best known results to date for n = 4, 6, 8, 10, and 16. Although it was not able to match the best known solution for n = 14, we observe that it improved the best known upper bound to date for n = 12 by almost 10%, producing a new, previously unknown solution whose carry-over effects value is 160.

The ILS phase of the heuristic terminates once 200 deteriorating moves have been accepted without improvement in the best solution found. For all classes of weighted instances, we observed that this counter very rarely reached values greater than 50. However, a very different behavior was noticed for the original, unweighted instances.

Instance	Avg. COEV	Best COEV	Avg. time	Worst time
inst4randomA	63.0	<u>63.0</u>	0.2	1.0
inst4randomB	53.0	53.0	0.2	1.0
inst4randomC	45.0	45.0	0.0	0.0
inst@randomA	233.0	233.0	0.0	1.0
inst6randomB	233.0	233.0 274.0	0.8	1.0
inst6randomC	235.0	235.0	1.2	2.0
inst8randomA	235.0 505.0	505.0	7.2	8.0
inst8randomB	495.0	495.0	18.6	20.0
inst8randomC	435.0	435.0	13.8	14.0
inst10randomA	912.6	470.0 895.0	13.8 139.4	150.0
inst10randomA			$159.4 \\ 151.0$	
	793.0	781.0		173.0
inst10randomC	744.6	737.0	149.0	172.0
inst12randomA	1549.2	1521.0	453.2	560.0
inst12randomB	1520.2	1489.0	402.4	451.0
inst12randomC	1594.4	1572.0	455.8	546.0
inst14randomA	2620.0	2608.0	39.8	44.0
inst14randomB	2903.8	2870.0	38.0	45.0
inst14randomC	2777.6	2760.0	36.8	42.0
inst16randomA	3812.2	3756.0	2605.8	2878.0
inst16randomB	3846.6	3797.0	2848.2	3294.0
inst16randomC	3773.6	3755.0	3138.0	3483.0
inst18randomA	5574.4	5515.0	1381.2	2442.0
inst18randomB	5816.2	5745.0	792.4	1271.0
inst18randomC	5598.0	5548.0	1547.2	3157.0
inst20randomA	7764.4	7760.0	136.8	145.0
inst 20 random B	7928.0	7888.0	147.8	174.0
inst 20 random C	7700.2	7636.0	136.8	144.0
Averages	2577.8	2555.8	542.3	711.8
inst4linear	20.0	20.0	0.2	1.0
inst6linear	114.0	114.0	0.6	1.0
inst8linear	168.0	168.0	8.4	9.0
inst10linear	318.0	318.0	64.6	70.0
inst12linear	504.0	496.0	271.4	309.0
inst14linear	960.0	958.0	18.6	20.0
inst16linear	1088.0	1076.0	2007.2	2313.0
inst 18 linear	1698.0	1660.0	4102.0	4729.0
inst20linear	2257.6	2212.0	5213.0	5624.0
Averages	792.0	780.2	1298.4	1452.9

Table 2 Results for random (upper part) and linear (lower part) instances.

In this case, many improvements obtained during the ILS phase were achieved after more than 50 deteriorating moves.

5 Concluding remarks

We discussed possible applications of the minimum carry-over effects value minimization problem as a fairness criterion to build good fixtures for round robin tournaments. A new, weighted version of the problem was introduced and formulated by integer programming, in which a weight is assigned to each pair of teams.

A hybrid heuristic based on the combination of the Iterated Local Search metaheuristic with a multistart strategy was proposed and applied to four classes of weighted problem instances with up to 20 teams. The weighted test instances are available from the authors for benchmarking purposes. Numerical results obtained for the original,

Instance	Avg. COEV	Best COEV	Avg. time	Longest time
inst4perturbedlinearA	16.0	16.0	0.2	1.0
inst4perturbedlinearB	17.0	17.0	0.2	1.0
inst4perturbedlinearC	22.0	22.0	0.0	0.0
inst6perturbedlinearA	68.0	68.0	1.4	2.0
inst6perturbedlinearB	73.0	73.0	0.6	1.0
inst6perturbedlinearC	60.0	60.0	0.8	1.0
inst8perturbedlinearA	137.0	137.0	31.0	32.0
inst8perturbedlinearB	141.0	141.0	22.4	23.0
inst8perturbedlinearC	162.0	162.0	26.8	28.0
inst10perturbedlinearA	329.0	326.0	136.0	162.0
inst10perturbedlinearB	277.0	274.0	134.0	163.0
inst10perturbedlinearC	291.8	284.0	128.6	152.0
inst12perturbedlinearA	601.2	587.0	484.2	638.0
inst12perturbedlinearB	528.6	525.0	494.6	580.0
inst12perturbedlinearC	486.6	478.0	546.6	648.0
inst14perturbedlinearA	940.0	920.0	42.8	45.0
inst14perturbedlinearB	947.4	932.0	39.8	43.0
inst14perturbedlinearC	993.2	990.0	36.2	40.0
inst16perturbedlinearA	1403.0	1376.0	3432.8	3905.0
inst16perturbedlinearB	1360.2	1348.0	3343.8	3668.0
inst16perturbedlinearC	1118.0	1098.0	3961.0	4683.0
inst18perturbedlinearA	2063.4	2005.0	5162.4	6983.0
inst18perturbedlinearB	1965.4	1921.0	4038.0	5343.0
inst18perturbedlinearC	1712.0	1585.0	4833.2	5805.0
inst20perturbedlinearA	3092.2	3065.0	482.0	1304.0
inst20perturbedlinearB	2866.8	2800.0	2923.4	4719.0
inst20perturbedlinearC	2837.2	2791.0	1479.6	3509.0
Averages	907.74	888.9	1177.1	1573.3
inst24brasileirao2003	7730.4	7542.0	13897.8	15755.0
inst24brasileirao2004	7179.6	7088.0	12992.8	13468.0
inst22brasileirao2005	5228.8	5158.0	10599.0	13959.0
inst20brasileirao2006	5310.0	5236.0	5705.4	6358.0
inst20brasileirao2007	4876.0	4834.0	2715.8	3655.0
inst20brasileirao2008	4045.6	3944.0	6805.6	8308.0
Averages	5728.4	5633.7	8786.1	10250.5

 Table 3 Results for perturbed linear (upper part) and real-life inspired (lower part) instances.

\overline{n}	Best to date	Hybrid	
	12	119.0110	
$\frac{4}{6}$	60	12 60	
8	56	56	
10^{8}	108	108	
-			(
12	176	160	(new best)
14	234	254	
16	240	240	

Table 4Results for the unweighted instances.

unweighted instances contributed to validate the effectiveness of the hybrid heuristic, which was even able to improve the best known solution to date for n = 12.

These results confirm previous successful cases of the hybridization of the Iterated Local Search metaheuristic with multistart strategies (e.g., as reported in [4,24,25]), in particular in the context of scheduling problems in sports.

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